1. Install “CSEG Actions Group” library: *CSEG_mini_actions*
    a. Download the .zip file (see the link in the class Notes)
    b. Extract the zip file
    c. Copy the zip file to your Arduino libraries location

2. Run the “CSEG Actions Group” library
    a. Stack two blocks about 2-3 block lengths in front of the robot arm
    b. Compile and upload to execute
    c. In the `user_task` function comment out the following line to run continuously:
    ```
    // step = 1;
    ```

3. Run the “CSEG Actions Group” library
    a. What changes can you make to the action group servo angles in *actions.h* to make the robot arm move more efficiently?
    b. Make those code changes to test your ideas